

$X(t)$ & $Y(t)$ are zero-mean random processes & uncorrelated.

Autocorrelation:

$$K_x(t, u) = f_1(t) f_1(u)$$

$$K_y(t, u) = f_2(t) f_2(u)$$

where $f_1(t) = \cos t$; $t \in [0, 2\pi]$

$$f_2(t) = \sin t$$

let $Z(t) = X(t) + Y(t) + N(t)$

$$K_n(t, u) = 0.5 \delta(t-u)$$

Find the eigen values & eigen functions of $K_z(t, u)$.

Soln: Since $X(t)$, $Y(t)$ & $N(t)$ are uncorrelated random processes.

$$\begin{aligned} K_z(t, u) &= E \{ Z(t) \cdot Z^*(u) \} \\ &= E \{ [X(t) + Y(t) + N(t)] \cdot [X(u) + Y(u) + N(u)]^* \} \\ &= E [X(t) \cdot X^*(u)] + E [Y(t) \cdot Y^*(u)] \\ &\quad + E [N(t) \cdot N^*(u)] \\ &= K_x(t, u) + K_y(t, u) + K_n(t, u) \end{aligned}$$

Reminder: separable kernels, i.e.

$$R_x(t, u) = f(t) \cdot f^*(u)$$

where $f(t)$ is deterministic, then,

$$\begin{aligned} \phi_i(t) &= \frac{f(t)}{\sqrt{E_f}} \\ \lambda_i &= E_f \end{aligned}$$

$$\phi_1(t) = \frac{f_1(t)}{\sqrt{E_{f_1}}} \quad \& \quad \phi_2(t) = \frac{f_2(t)}{\sqrt{E_{f_2}}}$$

$$E_{f_1} = \int_0^{2\pi} |f_1(t)|^2 dt$$

$$= \int_0^{2\pi} \cos^2 t dt$$

$$= \int_0^{2\pi} \left(\frac{1 + \cos 2t}{2} \right) dt$$

$$= \frac{1}{2} \left[t + \frac{\sin 2t}{2} \right]_0^{2\pi}$$

$$\underline{E_{f_1} = \frac{1}{2} [2\pi] = \pi}$$

$$; \quad E_{f_2} = \int_0^{2\pi} |f_2(t)|^2 dt$$

$$= \int_0^{2\pi} \sin^2 t dt$$

$$\underline{E_{f_2} = \pi}$$

to prove that $\phi_1(t)$ & $\phi_2(t)$ are orthogonal.

$$\langle f_1, f_2 \rangle = \int_0^{2\pi} f_1(t) \cdot f_2^*(t) dt$$

$$= \int_0^{2\pi} \cos t \cdot \sin t dt$$

$$= \int_0^{2\pi} \frac{1}{2} \sin 2t dt$$

$$= \frac{1}{2} \left[-\frac{\cos 2t}{2} \right]_0^{2\pi}$$

$$= 0$$

$$f_1(t) \perp f_2(t) \Rightarrow \underline{\phi_1(t) \perp \phi_2(t)}$$

The Eigen functions:

$$\phi_1(t) = \frac{1}{\sqrt{\pi}} \cos t, \quad \phi_2(t) = \frac{1}{\sqrt{\pi}} \sin t$$

$$\begin{aligned}
K_2(t, u) &= \mathbb{E} K_x(t, u) + K_y(t, u) + K_n(t, u) \\
&= f_1(t) f_1(u) + f_2(t) f_2(u) + 0.5 \delta(t-u) \\
&= \sqrt{\pi} \phi_1(t) \cdot \sqrt{\pi} \phi_1(u) + \sqrt{\pi} \phi_2(t) \cdot \sqrt{\pi} \phi_2(u) \\
&\quad + 0.5 \delta(t-u) \\
&= (\pi) \phi_1(t) \phi_1(u) + \pi \phi_2(t) \phi_2(u) + 0.5 \delta(t-u)
\end{aligned}$$

for white noise $N(t)$,

$$K_n(t, u) = \frac{N_0}{2} \delta(t-u)$$

$$\lambda_i = \frac{N_0}{2}$$

$\phi_i =$ any constant for all i

$$\delta(t-u) = \sum_i \phi_i(t) \phi_i^*(u)$$

also, we know that

if $r(t) = x(t) + n(t) \leftarrow$ white noise,

$$\text{then } \lambda_{r_i} = \lambda_{x_i} + \frac{N_0}{2}$$

$$\Rightarrow \left. \begin{aligned}
\lambda_1 &= \pi + 0.5, \quad \lambda_2 = \pi + 0.5 \\
\lambda_i &= 0.5 \quad \text{for } i=3, 4, 5, \dots
\end{aligned} \right\} \text{Eigen values}$$

$$\left. \begin{aligned}
\phi_1(t) &= \frac{\cos t}{\sqrt{\pi}}, \quad \phi_2 = \frac{\sin(t)}{\sqrt{\pi}} \\
\phi_i &= \text{constant for } i=3, 4, 5, \dots, \infty
\end{aligned} \right\} \text{Eigen functions}$$