

from eq. 2-8

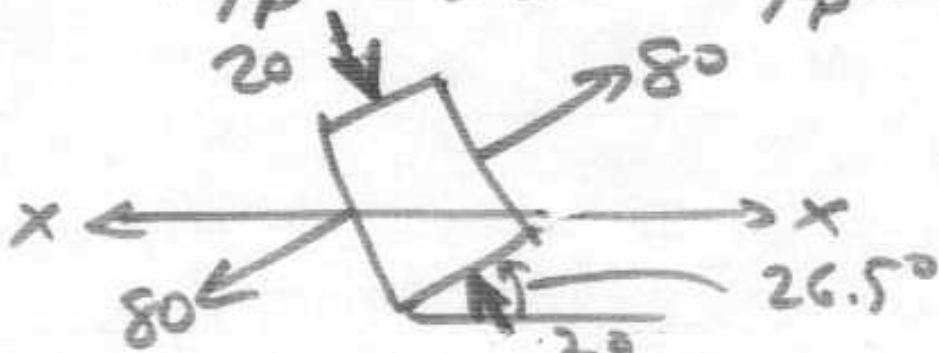
$$\sigma_1, \sigma_2 = \frac{60-0}{2} \pm \sqrt{\left(\frac{60-0}{2}\right)^2 + 40^2}$$

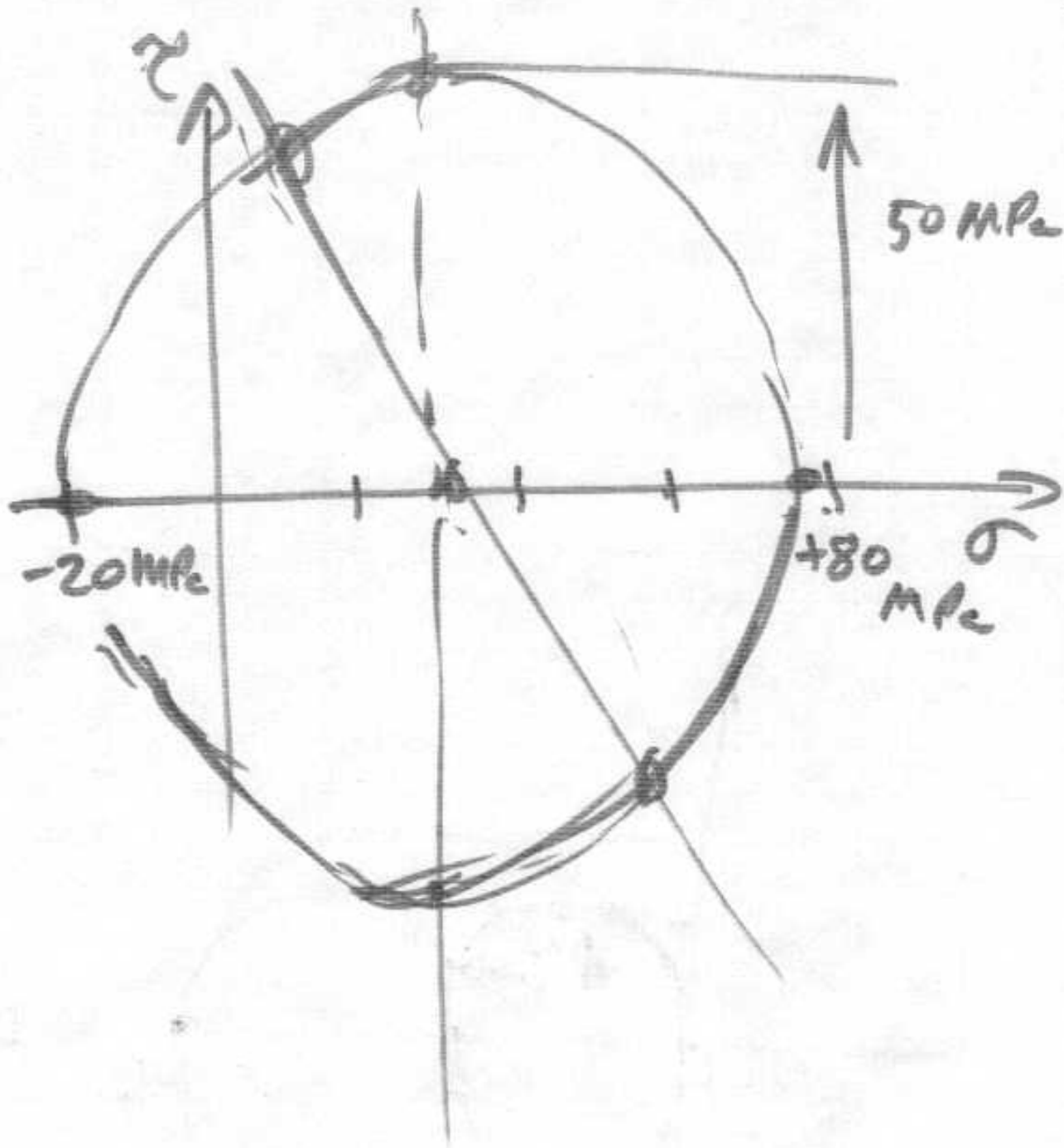
$$\sigma_1, \sigma_2 = 80, -20 \text{ MPa}$$

$$\begin{aligned} \gamma_{\max} &= 180(-20)/2 \\ &= 50 \text{ MPa} \end{aligned}$$

$$\tan 2\phi_p = \frac{2(40)}{60-0} = \frac{4}{3}$$

$$2\phi_p = 53^\circ \quad \phi_p = 26.5^\circ$$





25  
ALSO LOOK AT EXAMPLES

2-4, 2-5, 2-6

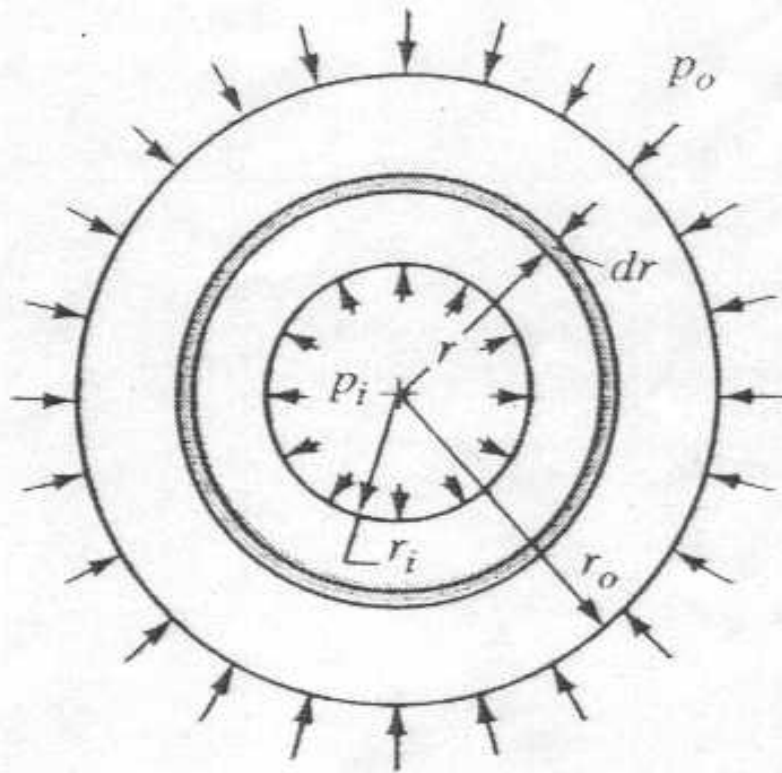
in text,

- No need to formally use vectors but you may if you are used to it

FIG 2-23

THICK-WALLED CYLINDERS

inner & outer pressures  $p_i \neq p_o$



$$\sigma_t = \frac{p_i r_i^2 - p_o r_o^2 - r_i^2 r_o^2 (p_o - p_i) / r^2}{r_o^2 - r_i^2}$$

$$\sigma_r = \frac{p_i r_i^2 - p_o r_o^2 + r_i^2 r_o^2 (p_o - p_i) / r^2}{r_o^2 - r_i^2}$$

NOTE: if  $r_i = 0$  (solid cylinder)

$$\sigma_{r_o} = -p_o \quad \text{and} \quad \tau_{t r_o} = 0$$

# Special case, $p_o = 0$

As usual, positive values indicate tension and negative values, compression.  
 The special case of  $p_o = 0$  gives

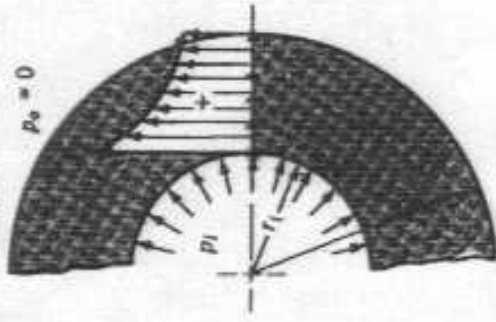
$$\sigma_r = \frac{r^2 p_i}{r_o^2 - r_i^2} \left( 1 + \frac{r_o^2}{r^2} \right) \quad (2-51)$$

$$\sigma_t = \frac{r^2 p_i}{r_o^2 - r_i^2} \left( 1 - \frac{r_o^2}{r^2} \right)$$

The equations of set (2-51) are plotted in Fig. 2-24 to show the distribution of stresses over the wall thickness.

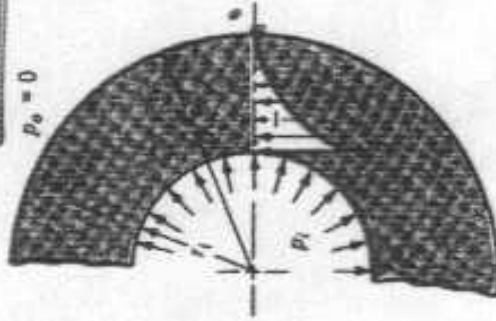
Tangential

Radial



(a) Tangential stress distribution

Tension



(b) Radial stress distribution

Compression

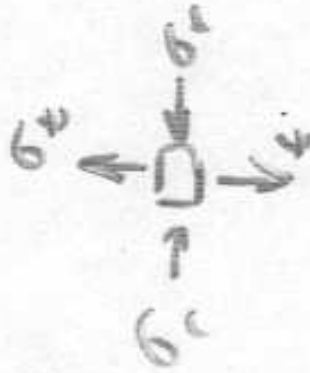
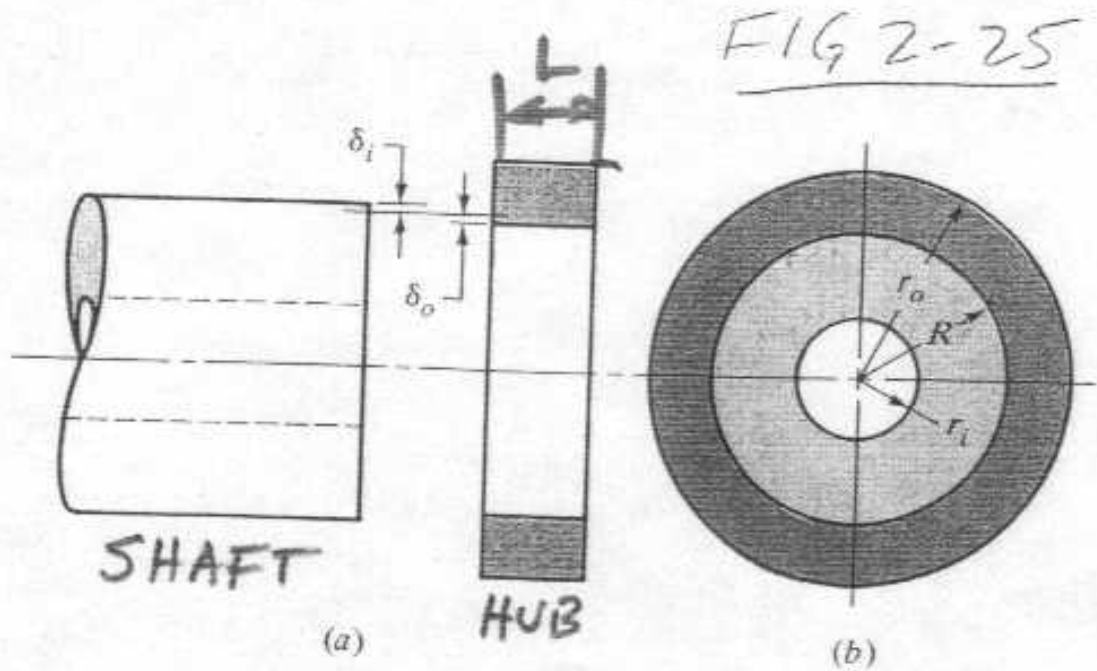


FIGURE 2-24  
 Distribution of stresses in a thick-walled cylinder subjected to internal pressure.

$$\delta = |\delta_i| - |\delta_o|$$



### PRESS FIT

#### GENERAL SITUATION:

SHAFT  $>$  nominal size by  $\delta_i$

HUB  $<$  nominal size by  $\delta_o$

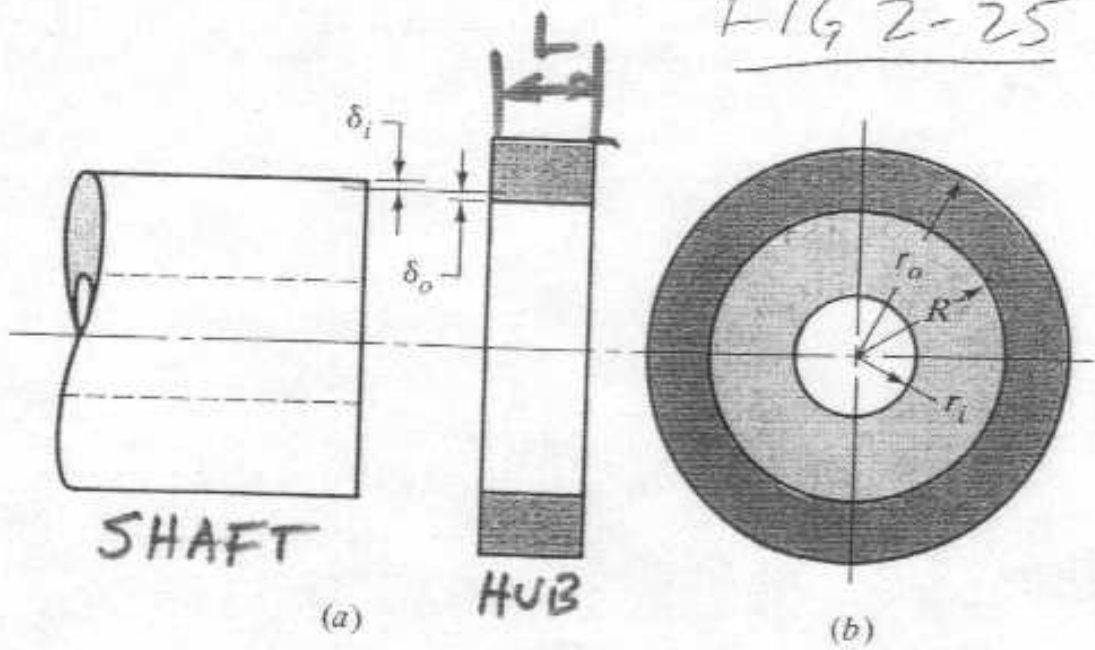
INTERFERENCE  $\delta = |\delta_i| + |\delta_o|$

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NOTE  $r_i \neq r_o$  have different meaning from single thick-walled cylinder eq's.

$$\delta = |\delta_i| - |\delta_o|$$

FIG 2-25



PRESS FIT

GENERAL SITUATION:

SHAFT  $>$  nominal size by  $\delta_i$

HUB  $<$  nominal size by  $\delta_o$

INTERFERENCE  $\delta = |\delta_i| + |\delta_o|$

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NOTE  $r_i \neq r_o$  have different meaning from single thick-walled cylinder eq's.

# STRESSES AT INTERFACE

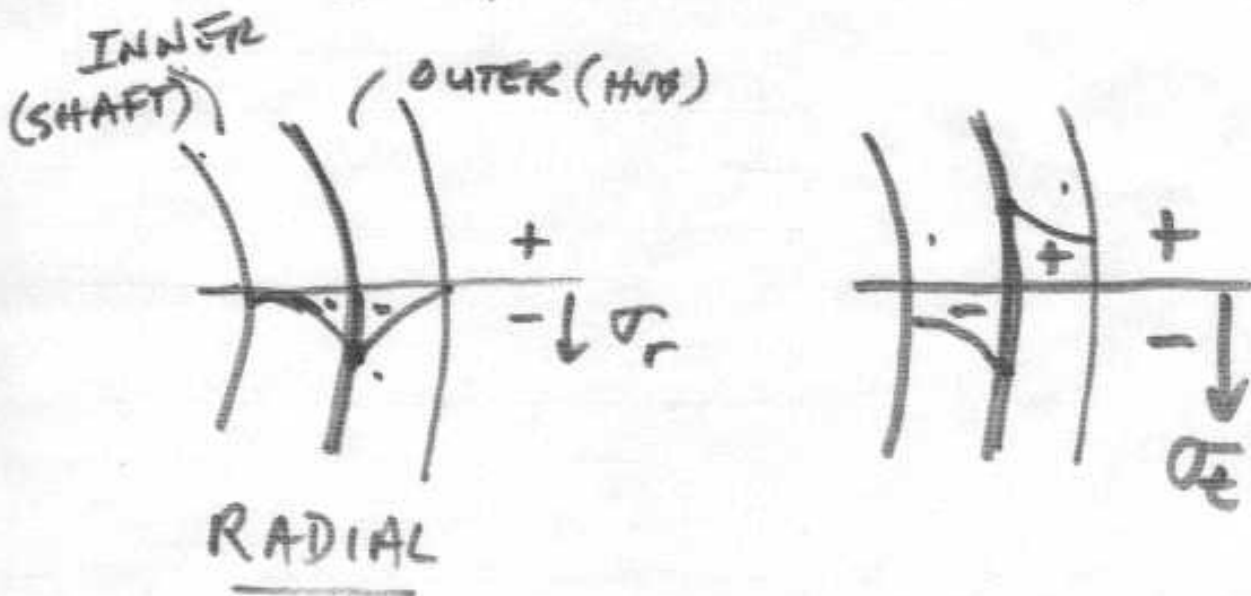
## TANGENTIAL

HUB IN TENSION

SHAFT IN COMPRESSION

## RADIAL

BOTH IN COMPRESSION





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APPLYING THICK-WALLED CYLINDER  
EQ FOR SHAFT & HUB

SHAFT @ R

$$\sigma_{it} = -p \frac{R^2 + r_i^2}{R^2 - r_i^2} \quad \dots 2.57$$

↙ PRESSURE @ INTERFACE

HUB

$$\sigma_{ot} = -p \frac{r_o^2 + R^2}{r_o^2 - R^2} \quad \dots 2.58$$

NEED TO FIND  $p$  @ INTERFACE

i.e.

$$\sigma_r = -p$$

THEN WE HAVE  $\sigma_t \neq \sigma_r$  values

The tangential (circumferential) strain  $\epsilon_{ot}$  can be related to both the interference:

$$\epsilon_{ot} = \frac{\delta_o}{R}$$

and the stress

$$\epsilon_{ot} = \frac{\sigma_{ot}}{E_o} - \frac{\nu \sigma_{or}}{E_o}$$

So that (using 2-57 & 2-58) we have

$$\delta_o = \frac{pR}{E_o} \left( \frac{r_o^2 + R^2}{r_o^2 - R^2} + \nu_o \right)$$

Similarly

$$\delta_i = \frac{pR}{E_i} \left( \frac{R^2 + r_i^2}{R^2 - r_i^2} - \nu_o \right)$$

recall That  $\delta = \delta_i + \delta_o$ , we  
can solve previous 2 eqs.  
for  $p$ . If one util  $E, \nu$

$$p = \frac{E\delta}{R} \left( \frac{(r_o^2 - R^2)(R^2 - r_i^2)}{2R(r_o^2 - r_i^2)} \right) \dots 2.60$$

note  $r_o > R$  and  $R > r_i$

$\therefore p$  is positive number  
but The radial stress  
at interface  $\sigma_r = -p$   
(i.e. compressive)

## Steel shaft & hub

e.g.  $r_i = 0$ ,  $R = 1''$   $r_o = 2''$

$$\delta = 0.002'' \quad E = 30 \times 10^6 \text{ psi}$$

from eq. 2-60

$$p = \frac{30 \times 10^6 \times 2 \times 10^{-3} \left( \frac{(2^2 - 1^2) 1^2}{2(1)(2^2)} \right)}{1}$$

$$= 30 \times 10^6 \times 2 \times 10^{-3} \times \frac{3}{8}$$

$$p = \underline{\underline{22.5 \times 10^3 \text{ psi}}}$$

1 inch length has area, A

$$\begin{aligned} \pi d(1) &= 2\pi R(1) = \\ &= \underline{\underline{12.56 \text{ in}^2}} \end{aligned}$$

$$N = \underline{\underline{282,000 \text{ lb}}}$$

$$\mu N = 0.3(282,000) = \underline{\underline{84,600 \text{ lb}}}$$

# SHRINK FIT

THE HUB IS SIZED SMALLER THAN THE SHAFT FOR PROPER INTERFERENCE.

HUB IS HEATED TO INCREASE ITS SIZE

$$\epsilon_T = \alpha \Delta T$$

COEF. OF THERMAL EXPANSION

$$\frac{\delta}{R} = \frac{\Delta R}{R} = \alpha \Delta T$$

IT'S SLIPPED ON AND ALLOWED TO COOL.

$$\left( \alpha_{\text{steel}} \approx 10^{-5} / ^\circ\text{C} \right) \left( 200^\circ\text{C} \text{ for previous example} \right)$$

## CONTACT STRESSES

- When convex-convex contacts or convex-concave contacts form localized contact stresses occur
- Can cause surface failure in ball bearings, roller bearings, gears, ball joints etc.
- General form of contact patch is ellipse
- we will look at circular and line contacts

# "Point Contacts"

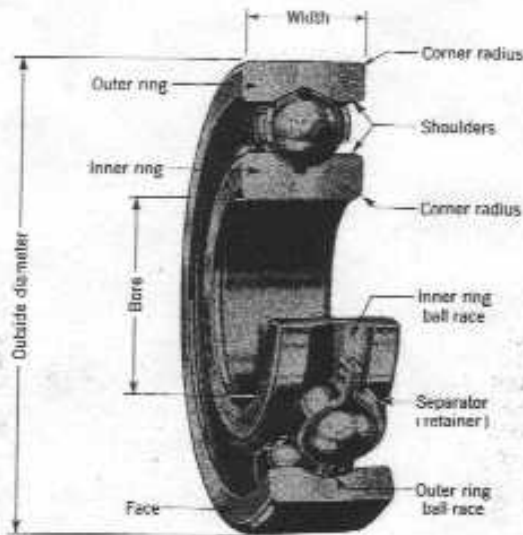
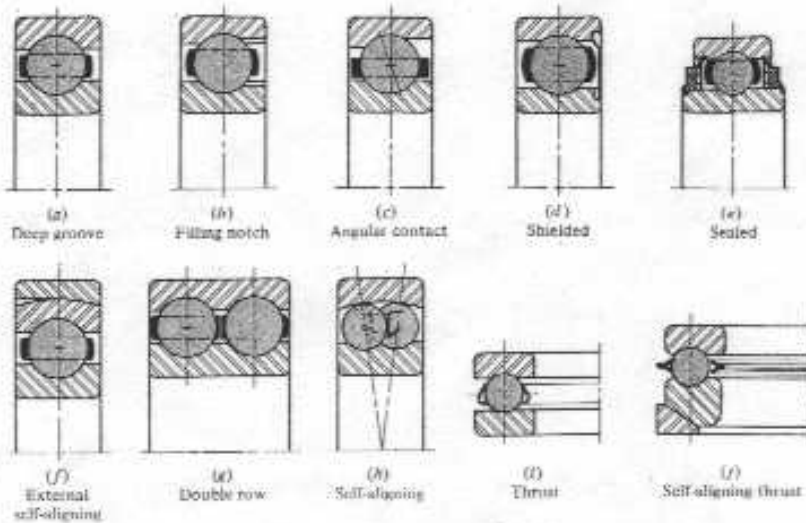


FIGURE 11-1  
Nomenclature of a ball bearing.  
(Courtesy of New Departure-Hyatt Division, General Motors Corporation.)

## Rolling-Contact Bearings 453



# "LINE CONTACTS"

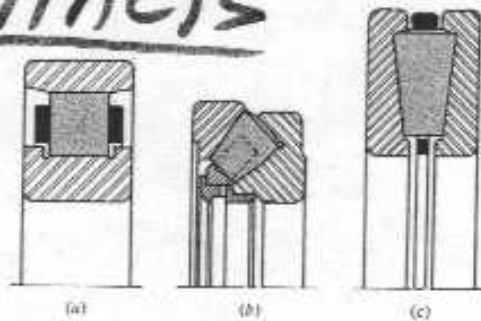


FIGURE 11-3

Types of roller bearings:  
 (a) straight roller; (b) spherical roller thrust; (c) tapered roller thrust; (d) needle; (e) tapered roller; (f) steep-angle tapered roller. (Courtesy of The Timken Company.)

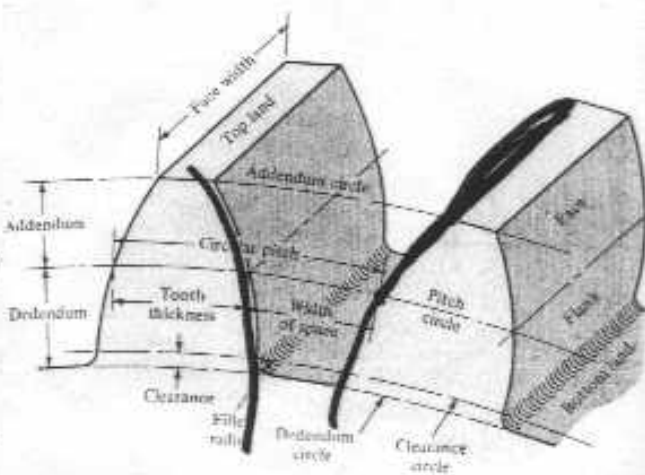
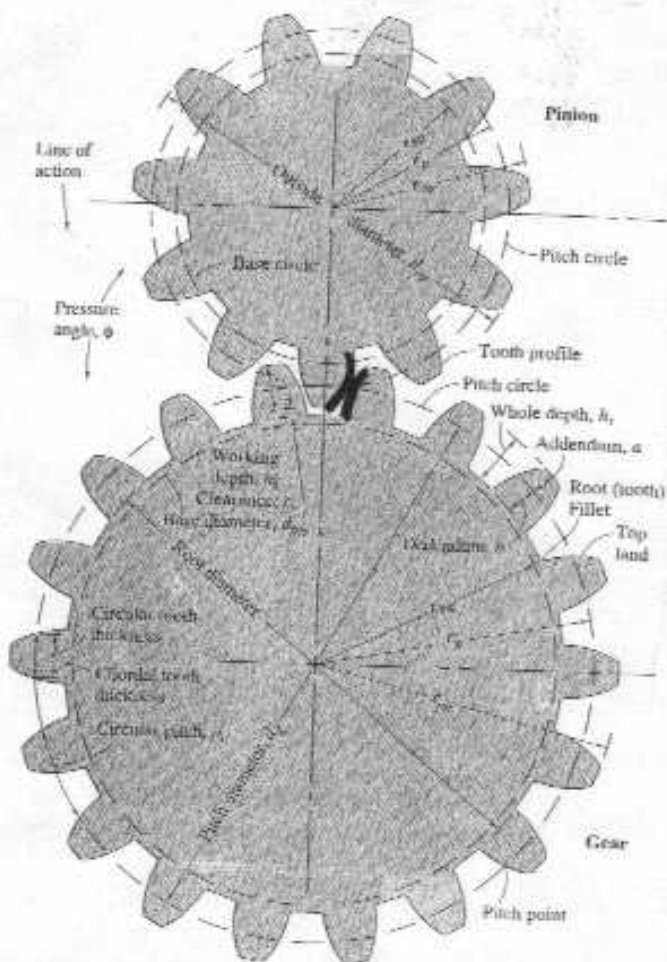
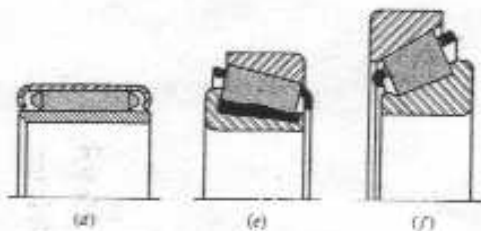




FIGURE 2-32

Two spheres held in contact by force  $F$ . Contact stress has an elliptical distribution at face of contact of width  $2a$ .

# CONTACT STRESSES

## SPHERES

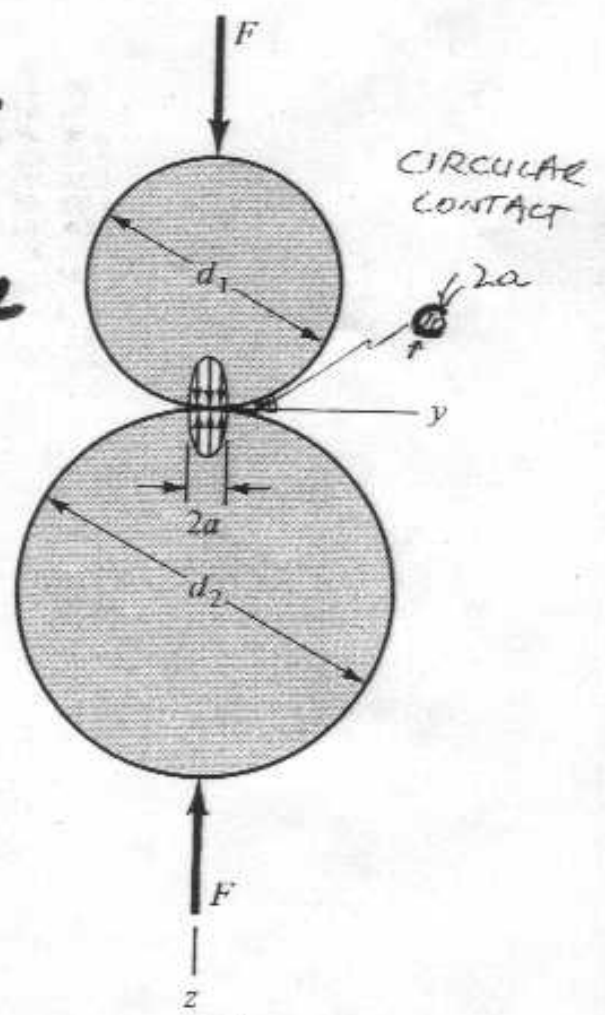
Avg contact pressure

$$p_a = \frac{F}{A} = \frac{F}{\pi a^2}$$

$$p_{max} = \frac{3}{2} p_a$$

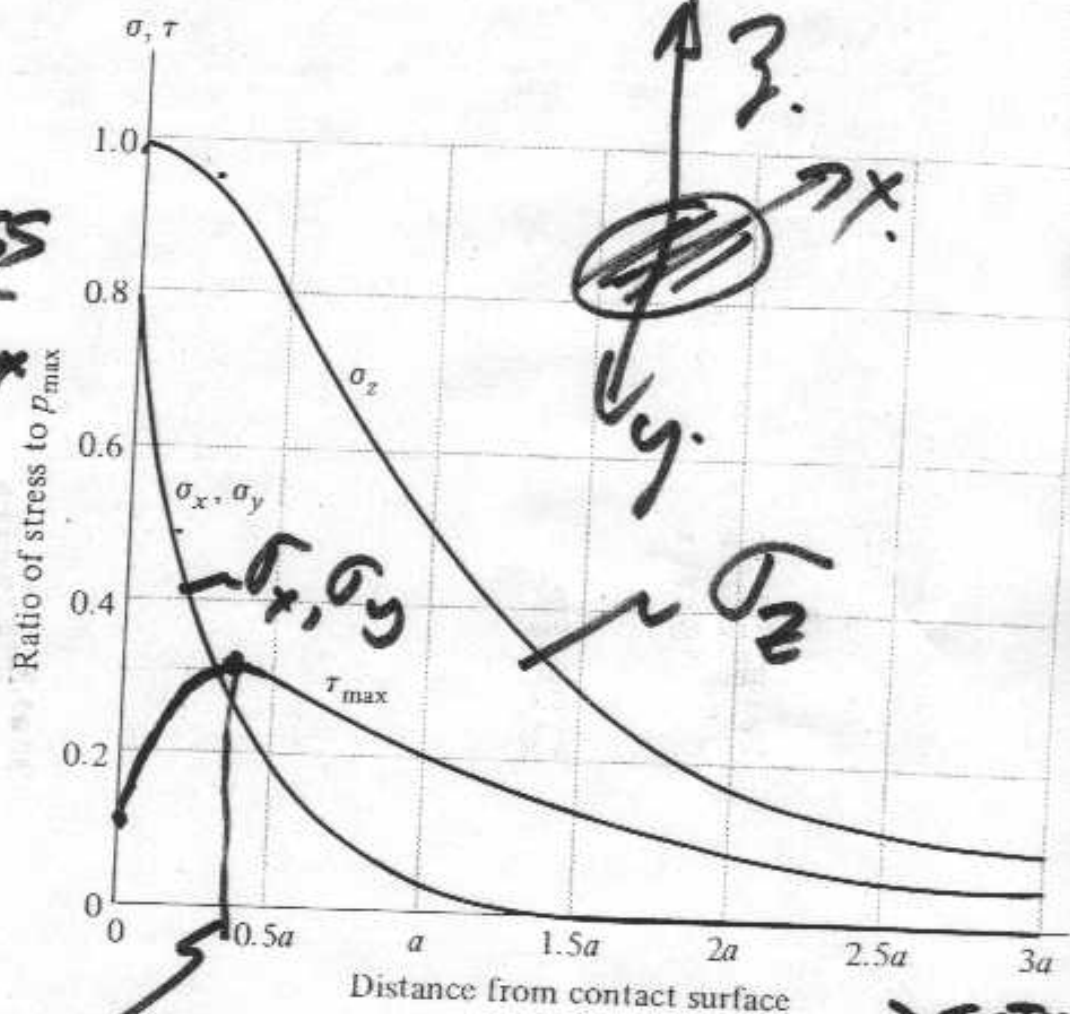
$$a = \sqrt[3]{\frac{3F}{8} \frac{(1 - \nu_1^2)/E_1 + (1 - \nu_2^2)/E_2}{1/d_1 + 1/d_2}}$$

$d$  positive for convex surface  
 $d$  negative for concave surface



FROM HERTZ THEORY

STRESS  
 $p_{max}$



- MAX SHEAR INCREASES WITH DEPTH UPTO  $0.4a$ .
- OPEN FAILURES START BELOW SURFACE

FIGURE 2-33

Magnitude of the stress components below the surface as a function of the maximum pressure for contacting spheres. Note that the maximum shear stress is slightly below the surface and is approximately  $0.3p_{max}$ . The chart is based on a Poisson's ratio of 0.30. Note that the normal stresses are all compressive stresses.

DEPTH  
BELOW  
SURFACE

## Example

TWO STEEL SPHERES  $d_1 = d_2 = d$   
 $E_1 = E_2 = E = 207 \text{ GPa}$   $= 10 \text{ mm}$

$$\nu_1 = \nu_2 = \nu = 0.3$$

$$F = 100 \text{ N}$$

FIND: Contact radius "a"

$p_{\text{max}}$

Location of max shear

$$a = \sqrt[3]{\frac{3F}{8} \frac{(1-\nu_1^2)/E_1 + (1-\nu_2^2)/E_2}{1/d_1 + 1/d_2}}$$

$$= \sqrt[3]{\frac{3F}{8} \frac{(2)(1-\nu^2)}{E} \cdot \frac{d}{(2)}}$$

$$a = \sqrt[3]{\frac{3F}{8} \frac{(1-\nu^2)d}{E}}$$

$$= \sqrt[3]{\frac{300}{8} \frac{(0.91)(0.01 \text{ m})}{207 \times 10^9 \text{ Pa}}}$$

$$a = 0.118 \times 10^{-3} \text{ m} = \underline{0.118 \text{ mm}}$$

$$p_{\max} = \frac{3F}{2\pi a^2} \quad @ \quad 0.4a = 0.05 \text{ mm} \\ = \underline{50 \mu\text{m}}$$

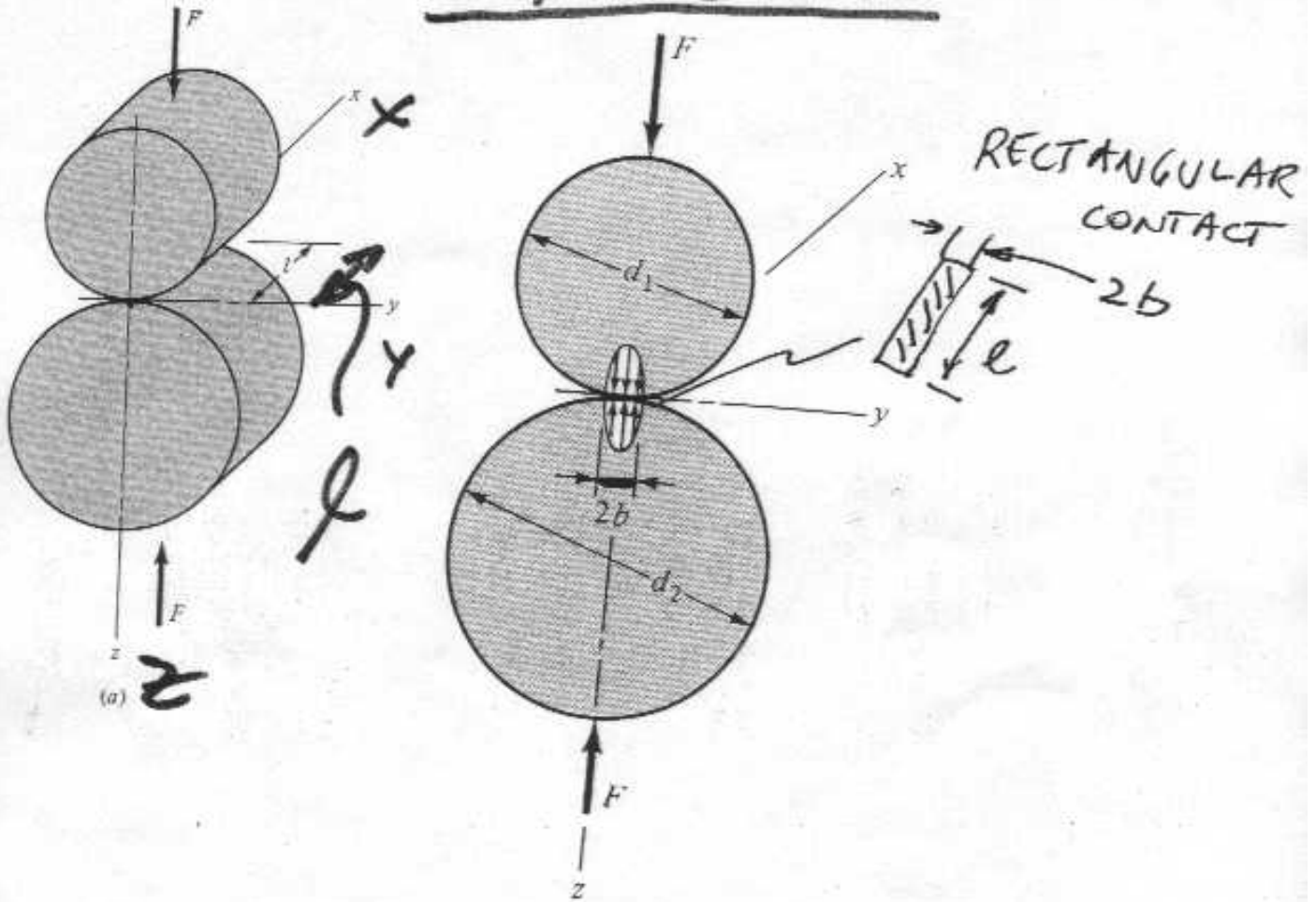
$$p_{\max} = 3.429 \text{ GPa}$$

$$= \underline{480,000 \text{ psi!}}$$

VERY HIGH ....

Expect plastic deformation

# CYLINDERS



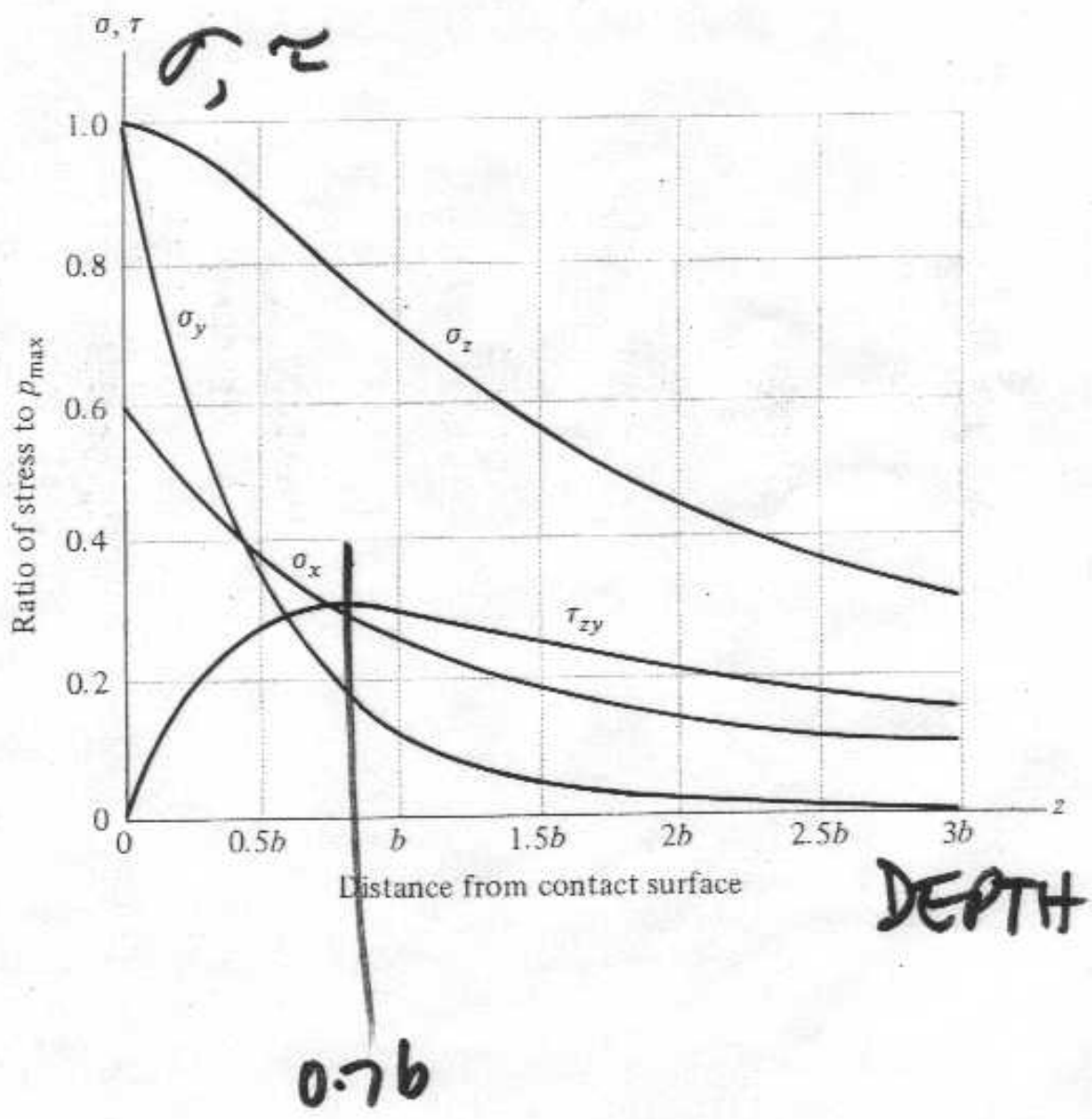
$$b = \sqrt{\frac{2F(1-\nu_1^2)/E_1 + (1-\nu_2^2)/E_2}{\pi l \left( \frac{1}{d_1} + \frac{1}{d_2} \right)}}$$

$$p_{max} = \frac{2F}{\pi b l}$$

FIGURE 2-34

(a) Two cylinders held in contact by force  $F$  uniformly distributed along cylinder length  $l$ . (b) Contact stress has an elliptical distribution at face of contact of width  $2b$ .

# CYLINDERS



Example: 2 Steel  
Cylinders  
 $d_1 = d_2 = 10 \text{ mm} = 0.01 \text{ m} = d$

$$\nu_1 = \nu_2 = 0.03 = \nu$$

$$E_1 = E_2 = E = 207 \text{ GPa}$$

$$F = 100 \text{ N} \quad l = 10 \text{ mm} = \underline{0.01 \text{ m}}$$

Find: b, p<sub>max</sub>, location of p<sub>max</sub>

$$b = \sqrt{\frac{2F(1-\nu^2)d}{\pi l E}}$$
$$= \sqrt{\frac{2(100)(0.91)(.01)}{\pi(0.01) 207 \times 10^9}}$$

$$b = 0.0167 \text{ mm} = \underline{1.67 \times 10^{-5} \text{ m}}$$